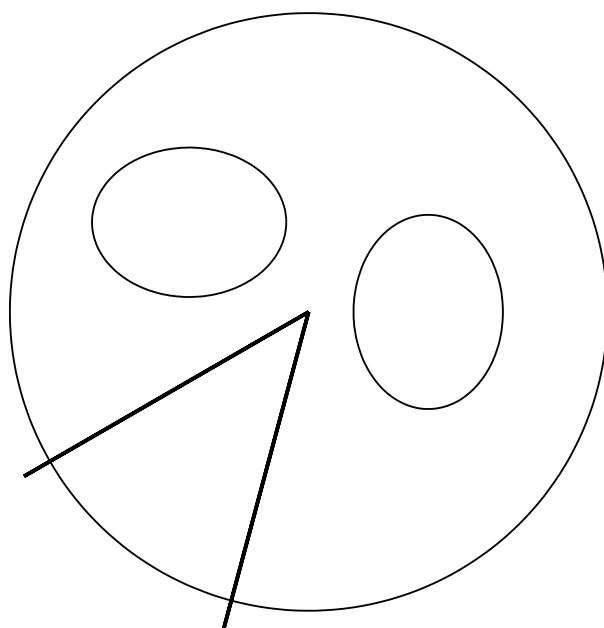


Electrical impedance tomography and Mittag-Leffler's function



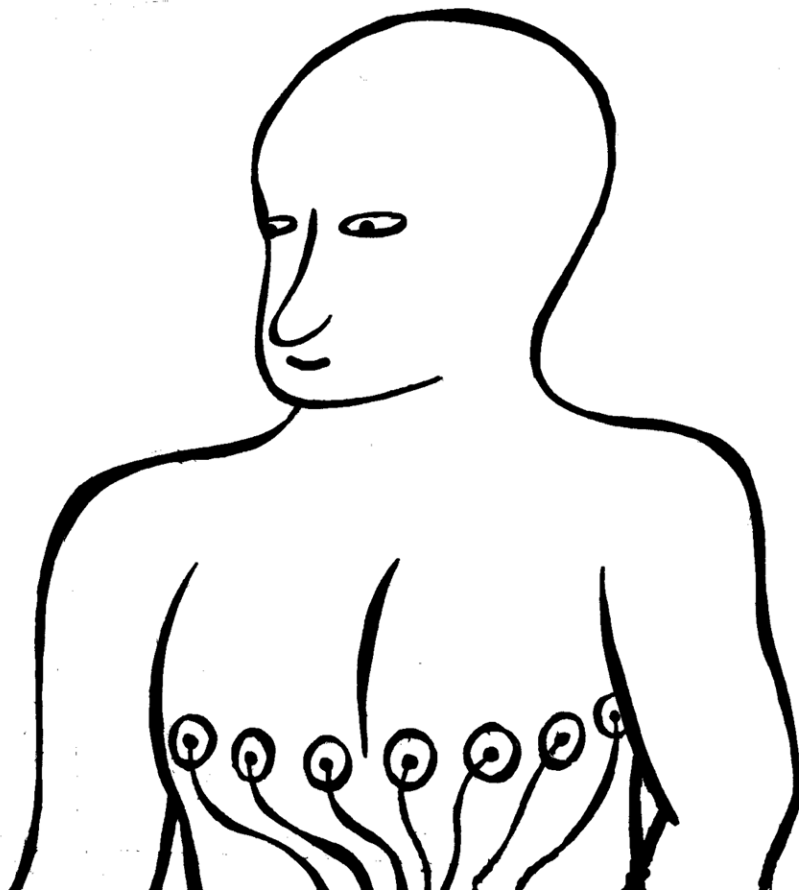
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JMS meeting, Chiba, Japan
September 27, 2003

Electrical impedance tomography (EIT) is a new medical imaging technique

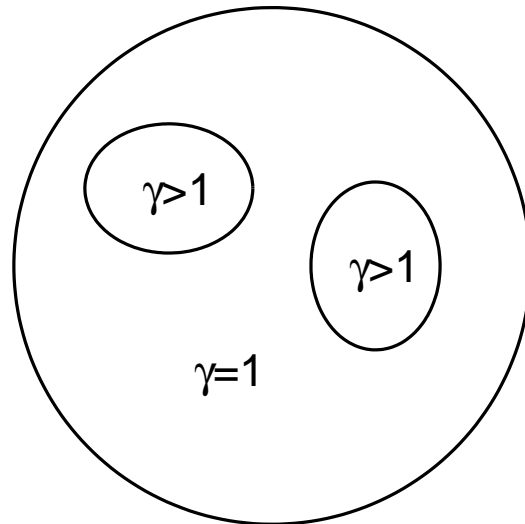


Feed electric currents through electrodes

Measure resulting voltages

Compute image of electrical conductivity
in the horizontal slice

Inverse conductivity problem
is the mathematical model of EIT



$\Omega \subset \mathbb{R}^2$ is unit disc, D is inclusion with $\gamma > 1$

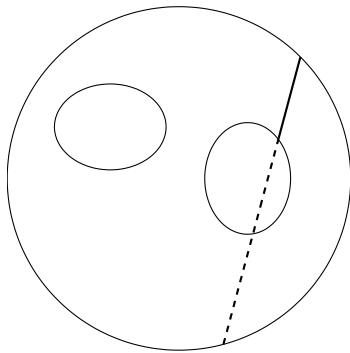
Problem in our case: Recover D

from the current-to-voltage map R_γ

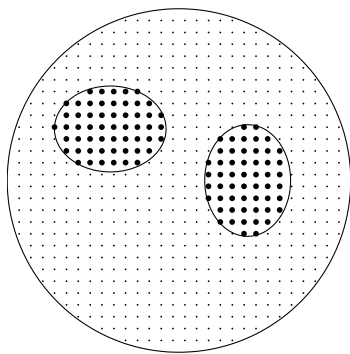
$$R_\gamma f = u|_{\partial\Omega} - \frac{1}{|\partial\Omega|} \int_{\partial\Omega} u,$$

$$\begin{cases} \nabla \cdot \gamma \nabla u = 0 & \text{in } \Omega, \\ \frac{\partial u}{\partial \nu} = f & \text{on } \partial\Omega. \end{cases}$$

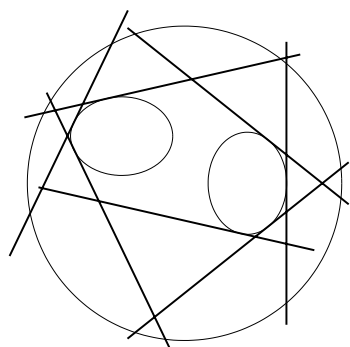
Many methods for recovering D from R_γ have been suggested



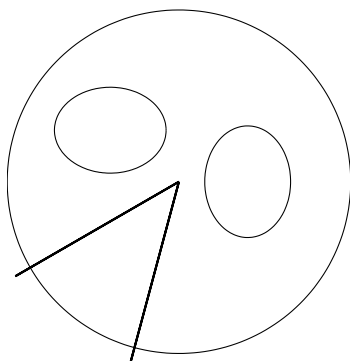
Probe method by Ikehata



Adaptation of Kirsch's method by Brühl and Hanke



Enclosure method by Ikehata, S for finding the convex hull of D



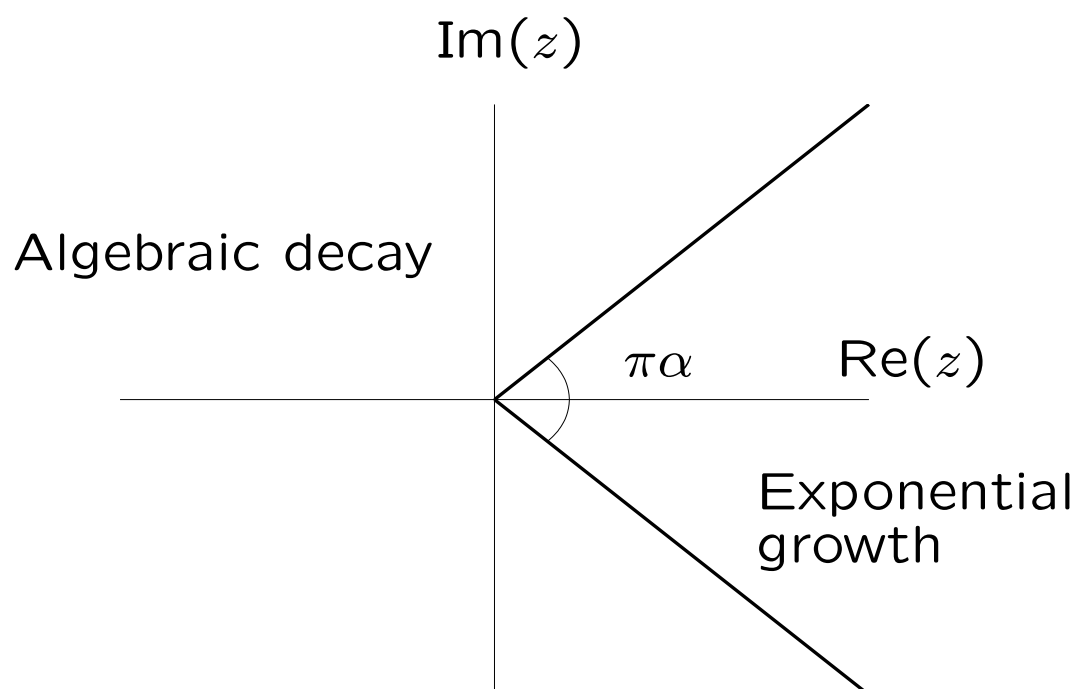
The present approach generalizes the enclosure method

Mittag-Leffler's function $E_\alpha(z)$: definition and asymptotic behavior

E_α is the entire function given by

$$E_\alpha(z) = \sum_{m=0}^{\infty} \frac{z^m}{\Gamma(\alpha m + 1)}.$$

Asymptotic behavior of $|E_\alpha(z)|$ as $|z| \rightarrow \infty$:



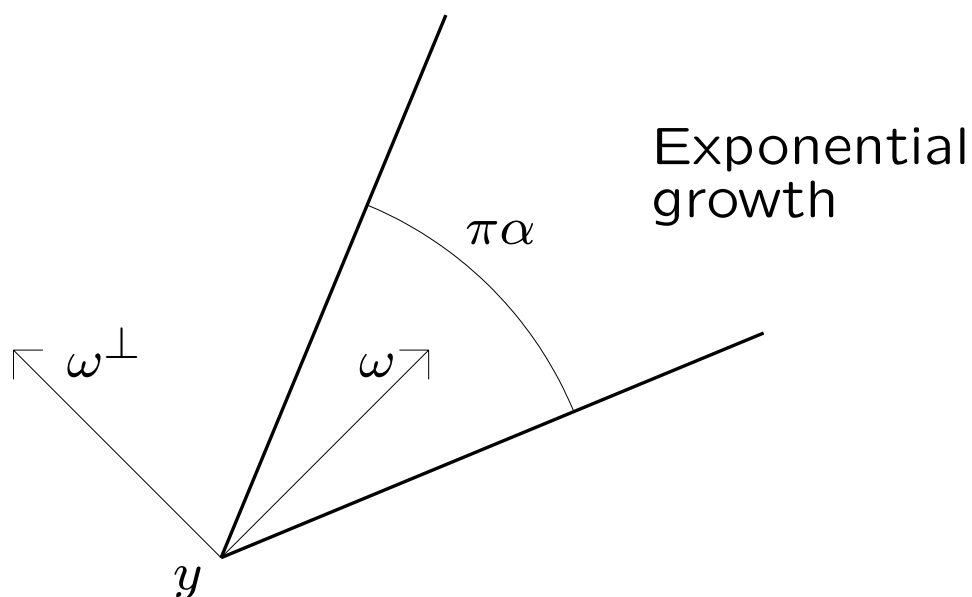
**Indicator function is the key object
for recovering D from R_γ**

$$I_{(y,\omega)}^\alpha(\tau) = \int_{\partial\Omega} \frac{\overline{\partial e_\tau^\alpha}}{\partial\nu} (R_1 - R_\gamma) \frac{\partial e_\tau^\alpha}{\partial\nu} d\sigma,$$

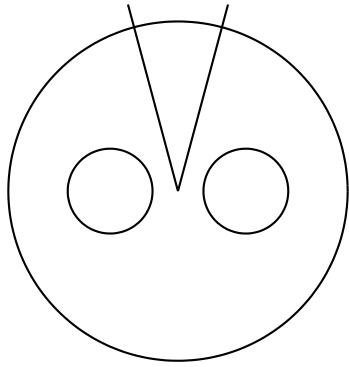
where we set for $\tau > 0$

$$e_\tau^\alpha(x; y, \omega) = E_\alpha(\tau\{(x - y) \cdot \omega + i(x - y) \cdot \omega^\perp\}).$$

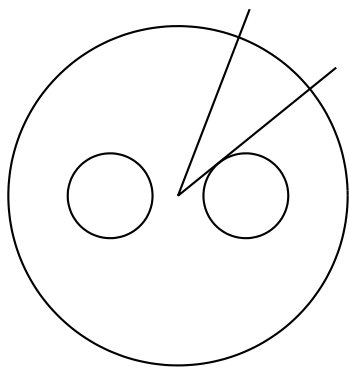
Asymptotic behavior of e_τ^α when $\tau \rightarrow \infty$:



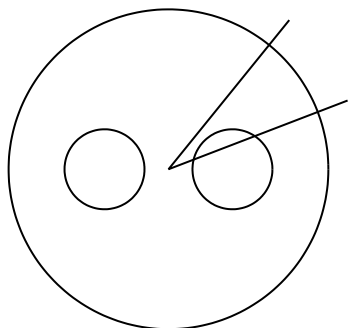
Indicator function is used to determine if a given cone intersects D



$$\lim_{\tau \rightarrow \infty} |I_{(y,\omega)}^\alpha(\tau)| = 0$$



$$\liminf_{\tau \rightarrow \infty} |I_{(y,\omega)}^\alpha(\tau)| > 0$$



$$\lim_{\tau \rightarrow \infty} |I_{(y,\omega)}^\alpha(\tau)| = \infty$$

Reconstruction from measured data restricts the use of indicator function

$$I_{(y,\omega)}^\alpha(\tau) = \int_{\partial\Omega} \overline{\frac{\partial e_\tau^\alpha}{\partial \nu}} (R_1 - R_\gamma) \frac{\partial e_\tau^\alpha}{\partial \nu} d\sigma$$

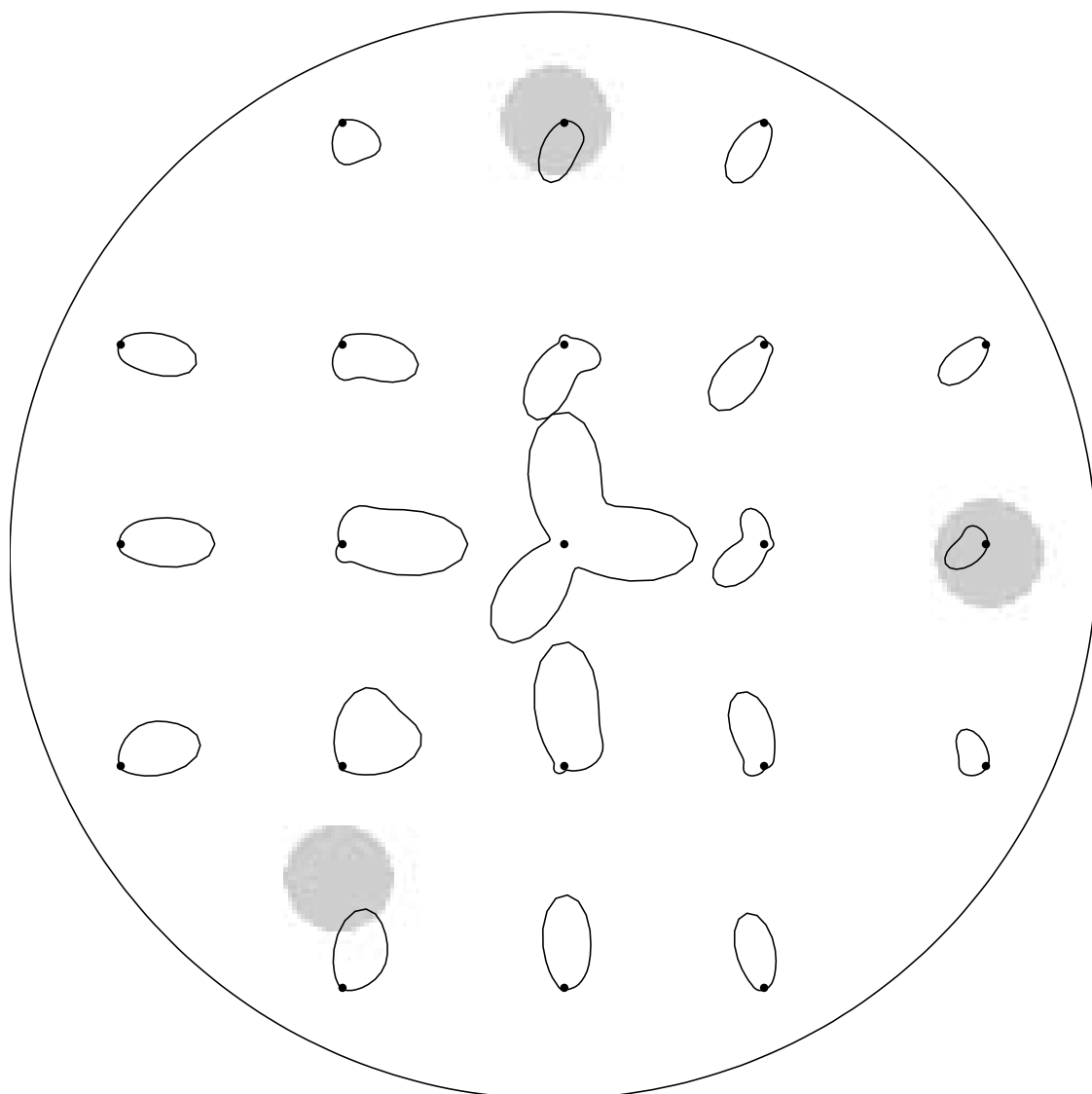
In practice, R_γ is a 16×16 matrix with random error in the elements

The functions $\overline{\frac{\partial e_\tau^\alpha}{\partial \nu}}$ and $\frac{\partial e_\tau^\alpha}{\partial \nu}$ are expressed as truncated Fourier series

Consequently, maximum $\tau = \frac{1}{2} \neq \infty$

**We recover D in three steps
from the practical indicator function:**

1. Exclude cones with small $|I_{(y,\omega)}^{1/2}(\frac{1}{2})|$.
2. Use local maxima to assign values to non-excluded y .
3. Recover D as a level set of the function resulting from step 2.



Three reconstructions

