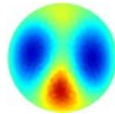


New computational methods for electrical impedance tomography

Samuli Siltanen
GE Healthcare Finland
Samuli.siltanen@iki.fi

SciCADE 2005, Nagoya, Japan

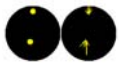


This is a joint work with

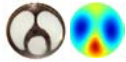
- Masaru Ikehata** Gunma University, Japan
- David Isaacson** Rensselaer Polytechnic Institute, USA
- Kim Knudsen** Aalborg University, Denmark
- Matti Lassas** Helsinki University of Technology, Finland
- Jennifer Mueller** Colorado State University, USA
- Jon Newell** Rensselaer Polytechnic Institute, USA



$$\Lambda_\gamma f = \gamma \frac{\partial u}{\partial \nu} \Big|_{\partial \Omega} \quad \text{Introduction to EIT}$$

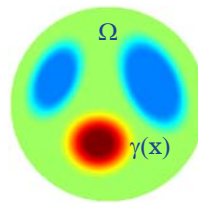


EIT meets Mittag-Leffler



D-bar method for EIT

The inverse conductivity problem of Calderón is mathematical model of EIT



$$\Lambda_\gamma f = \gamma \frac{\partial u}{\partial \nu} \Big|_{\partial \Omega},$$

$$\begin{aligned} \nabla \cdot \gamma \nabla u &= 0 \quad \text{in } \Omega, \\ u &= f \quad \text{on } \partial \Omega. \end{aligned}$$

Given the Dirichlet-to-Neumann map,
how to reconstruct the conductivity?
The reconstruction problem is nonlinear and ill-posed.

The uniqueness question in 2-D has been studied by these authors

- 1980 Calderón
- 1985 Kohn and Vogelius
- 1987 Sylvester and Uhlmann ($n > 2$)
- 1987 R G Novikov ($n > 2$)
- 1988 Nachman ($n > 2$)
- 1996 Nachman
- 1997 Brown and Uhlmann
- 2003 Astala and Päivärinta



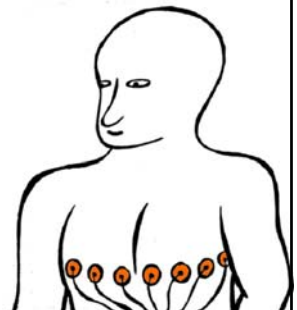
5 / GE 7

Applications of EIT to medical imaging

Feed electric currents through electrodes, measure voltages

Reconstruct the image of electric conductivity in a two-dimensional slice

Clinical tasks:
monitoring heart and lungs of SARS patients,
detecting pulmonary edema (swollen lungs)



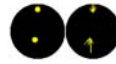
Nondestructive testing and EIT



Finding cracks or defects in known background.
 Photo from: Shigo, A.L., 1983. *Tree Defects: A Photo Guide*.
 USDA Forest Service, No. Cent. For. Exp. Sta., GTRNE-82.

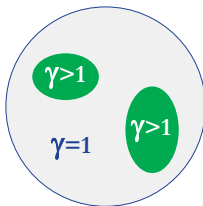


21 / 46



EIT meets Mittag-Leffler

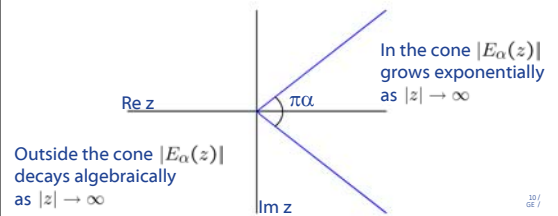
We consider recovering an inclusion in homogeneous background



22 / 46

Mittag-Leffler's function: definition and asymptotic behavior

$$E_\alpha(z) = \sum_{m=0}^{\infty} \frac{z^m}{\Gamma(\alpha m + 1)}$$



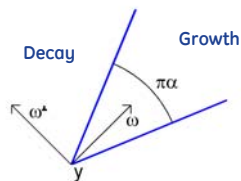
23 / 46

Indicator function is the key object for recovering inclusions from ND map

$$I_{(y,\omega)}^\alpha(\tau) = \int_{\partial\Omega} \frac{\partial e_\tau^\alpha}{\partial \nu} (R_1 - R_\tau) \frac{\partial e_\tau^\alpha}{\partial \nu} d\sigma,$$

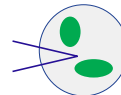
$$e_\tau^\alpha(x; y, \omega) = E_\alpha(\tau\{(x-y)\cdot\omega + i(x-y)\cdot\omega^\perp\}).$$

Asymptotic behavior of e_τ^α as $|z| \rightarrow \infty$:

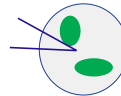


24 / 46

Theorem: we can find out if a given cone intersects the inclusion



$$\lim_{\tau \rightarrow \infty} |I_{(y,\omega)}^\alpha(\tau)| = 0$$



$$\liminf_{\tau \rightarrow \infty} |I_{(y,\omega)}^\alpha(\tau)| > 0$$



$$\lim_{\tau \rightarrow \infty} |I_{(y,\omega)}^\alpha(\tau)| = \infty$$

25 / 46

Indicator function can be written in terms of the measured ND map

$$\text{Write } I_{(y,\omega)}^\alpha(\tau) = \int_{\partial\Omega} \frac{\partial e_\tau^\alpha}{\partial \nu} (R_1 - R_\gamma) \frac{\partial e_\tau^\alpha}{\partial \nu} d\sigma,$$

and expand the function $\frac{\partial e_\tau^\alpha}{\partial \nu}$ in Fourier basis to get

$$I_{(y,\omega)}^{1/n,mN}(\tau) = 2\pi \sum_{1 \leq m, \ell \leq nN} \frac{\tau^{m+\ell} \omega^m \omega^\ell}{\Gamma(\frac{m}{n} + 1) \Gamma(\frac{\ell}{n} + 1)}$$

$$\times \sum_{r_1=1}^m \sum_{r_2=1}^\ell \binom{m}{r_1} \binom{\ell}{r_2} r_1 r_2 (-1)^{m+\ell-r_1-r_2} y^{m-r_1} y^{\ell-r_2}$$

$$\times (\mathcal{R}_1[r_2, r_1] - \mathcal{R}_\gamma[r_2, r_1]).$$

37 / 42

Due to finite number of measurements, we cannot take τ to infinity

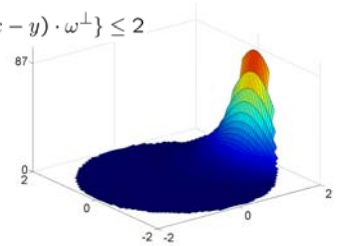
The truncated power series of Mittag-Leffler's function gives relative accuracy of 1% for $|z| < 2$.

We evaluate Mittag-Leffler's function at

$$\tau \{(x-y) \cdot \omega + i(x-y) \cdot \omega^\perp\} \leq 2$$

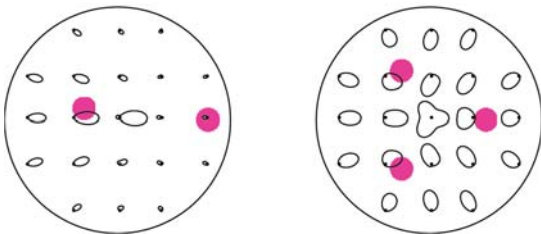
Thus we choose

$$\tau(y) = \frac{1}{1 + |y|}$$



38 / 42

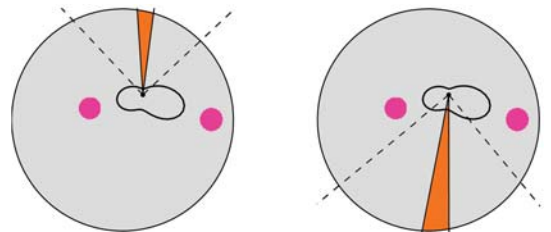
Indicator functions with fixed y and plotting $|I(y,\omega)|$ in polar coordinates



39 / 42

40 / 42

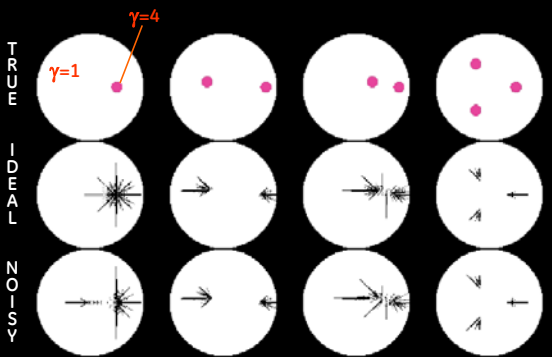
We exclude cones corresponding to local minima of the indicator function



41 / 42

42 / 42

Numerical recovery of disc inclusions



 D-bar method for EIT

Nachman's reconstruction method [Ann of Math 1996] consists of two steps

$$\Lambda_\gamma \rightarrow \mathbf{t} \rightarrow \gamma$$

The intermediate object \mathbf{t} is the *scattering transform*



21 / 66 /

Step 1: given noisy data, compute approximate scattering transform

Approximate scattering transform:

$$\mathbf{t}^{\text{exp}}(k) = \int_{\partial\Omega} e^{i\bar{k}\bar{x}} (\Lambda_\gamma - \Lambda_1) e^{ikx} d\sigma(x)$$

Regularize computation by truncation:

$$\mathbf{t}_R^{\text{exp}}(k) := \begin{cases} \mathbf{t}^{\text{exp}}(k), & |k| < R, \\ 0, & |k| \geq R. \end{cases}$$



22 / 66 /

Step 2: solve d-bar equation with approximate kernel

Write the approximate dbar equation

$$\frac{\partial}{\partial \bar{k}} \mu_R(x, k) = \frac{\mathbf{t}_R^{\text{exp}}(k)}{4\pi \bar{k}} e^{-i(kx + \bar{k}\bar{x})} \overline{\mu_R(x, k)}$$

In integral form:

$$\mu_R(x, k) = 1 + \frac{1}{\pi k} * \left(\frac{\mathbf{t}_R^{\text{exp}}(k)}{4\pi \bar{k}} e^{-i(kx + \bar{k}\bar{x})} \overline{\mu_R(x, k)} \right)$$

This Lippmann-Schwinger -type equation can be solved numerically with modified Vainikko's algorithm. Then

$$\gamma_R^{1/2}(x) = \mu_R(x, 0).$$



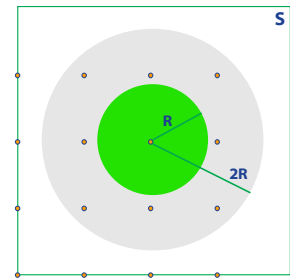
23 / 66 /

Define a grid for Vainikko's algorithm

$(2^m \times 2^m)$ points in the square S in the k -plane.

Here $m=2$, in practice typically $m=8$.

This grid is suitable for the use of Fast Fourier Transform (FFT).



24 / 66 /

The d-bar equation can be solved using periodization

Instead of the d-bar equation

$$\mu_R(x, k) = 1 + \frac{1}{\pi k} * \left(\frac{\mathbf{t}_R^{\text{exp}}(k)}{4\pi \bar{k}} e^{-i(kx + \bar{k}\bar{x})} \overline{\mu_R(x, k)} \right)$$

valid in the k -plane, we solve the S -periodic equation

$$\left[I + \frac{1}{\pi k} * (T_R \cdot \bar{\cdot}) \right] w = 1$$

$$T_R(k) = - \frac{\mathbf{t}_R^{\text{exp}}(k)}{4\pi \bar{k}} e^{-i(kx + \bar{k}\bar{x})}$$

The d-bar equation is also solved since

$$\mu_R(x, \cdot)|_{B(0, R)} = w|_{B(0, R)}$$

25 / 66 /

Vainikko's method is based on iterative solution of linear equations

We can solve the discretized equation

$$\left[I + \frac{1}{\pi k} * (T_R \cdot \bar{\cdot}) \right] w = 1$$

using the iterative GMRES method.

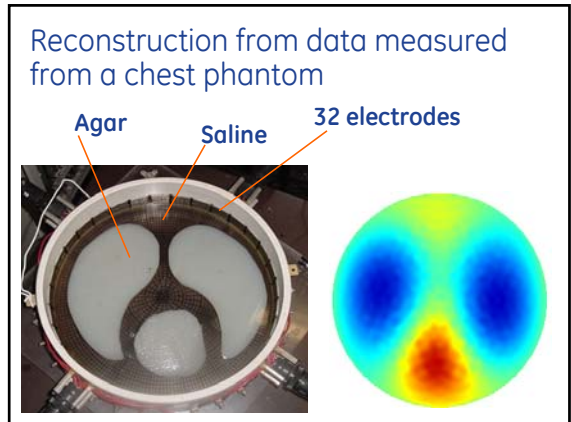
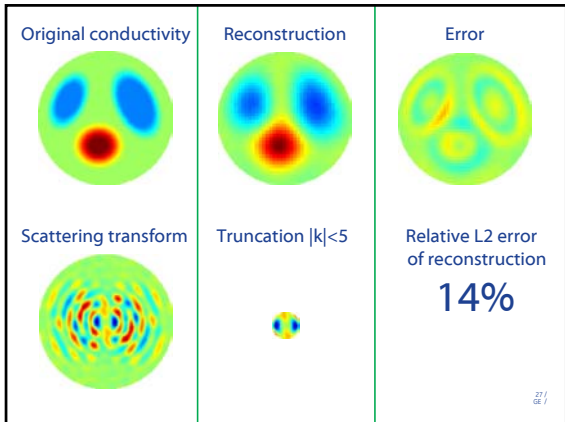
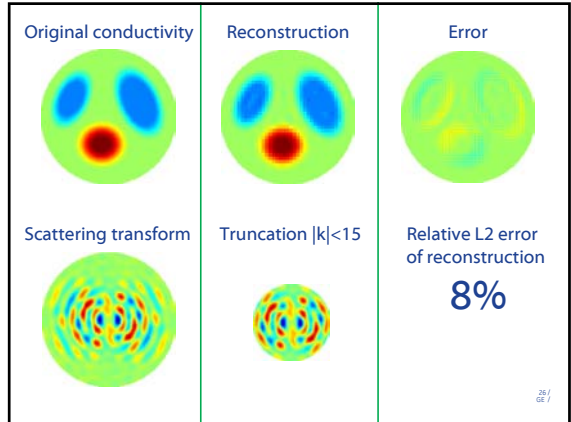
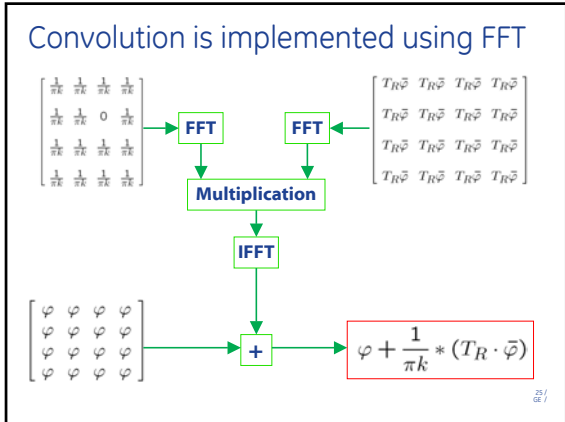
We just need to implement the formula

$$\varphi + \frac{1}{\pi k} * (T_R \cdot \bar{\varphi})$$

for a function ϕ given on the grid points.



26 / 66 /



Ikehata M and Siltanen S 2000 Numerical method for finding the convex hull of an inclusion in conductivity from boundary measurements, *Inverse Problems* 16, pp. 1043-1052

Ikehata M and Siltanen S 2004 Electrical impedance tomography and Mittag-Leffler's function, *Inverse Problems* 20, pp. 1325-1348

Isaacson D, Mueller J L, Newell J and Siltanen S 2004 Reconstructions of chest phantoms by the d-bar method for electrical impedance tomography, *IEEE Transactions on Medical Imaging* 23(7), pp. 821-828

Knudsen K, Mueller J L and Siltanen S 2004 Numerical solution method for the dbar-equation in the plane, *J Comp Phys* 198(2), pp. 500-517

Mueller J L and Siltanen S 2003 Direct reconstructions of conductivities from boundary measurements, *SIAM J Sci Comp* 24(4), pp. 1232-1266

Siltanen S, Mueller J L and Isaacson D 2000 An implementation of the reconstruction algorithm of A. Nachman for the 2-D inverse conductivity problem, *Inverse Problems* 16, pp. 681-699; Erratum, *Inverse problems* 17